

THE ROLE OF STABILITY IN THE UNIFICATION OF MECHANICS AND THERMODYNAMICS

GIAN PAOLO BERETTA

Massachusetts Institute of Technology, Cambridge, Mass., USA
and Università di Brescia, Brescia, Italy

ACADEMIE NATIONALE
DE L'AIR ET DE L'ESPACE

O.N.E.R.A. - CERT

Colloque International sur
LA STABILITE

International Symposium on
STABILITY

RECUEIL DES CONFERENCES

PROCEEDINGS

PARIS

3-4-5 NOVEMBRE 1987

ACADEMIE NATIONALE DE
L'AIR ET DE L'ESPACE

1, avenue Camille Flammarion
31500 TOULOUSE
FRANCE

CENTRE D'ETUDES ET DE
RECHERCHES DE TOULOUSE

Complexe Aérospatial
Boite Postale 4025
31055 TOULOUSE Cedex FRANCE

THE ROLE OF STABILITY IN THE UNIFICATION OF MECHANICS AND THERMODYNAMICS

GIAN PAOLO BERETTA

Massachusetts Institute of Technology, Cambridge, Mass., USA
and Università di Brescia, Brescia, Italy

ABSTRACT

Stability plays a crucial role in the second law of Thermodynamics. The states of Equilibrium Thermodynamics are not simply equilibrium but, most importantly, they are the only stable equilibrium states a system may and must admit. The very demanding second-law requirement of existence and uniqueness of the stable equilibrium states, has provided strong guidance towards the resolution of the century-old dilemma on the meaning of thermodynamic entropy and the nature of irreversibility. It has led to the formulation of a new theory, Quantum Thermodynamics, which encompasses within a single, uncontradictory structure the whole of Quantum Mechanics and Equilibrium Thermodynamics, as well as the successful part of Statistical Mechanics, namely, its mathematical formalism. The new theory resolves the conceptual inconsistencies of Statistical Mechanics and opens new vistas on the description of nonequilibrium dynamics.

1. INTRODUCTION

There is no dispute about the results, the mathematical formalism, and the practical consequences of the theories of Mechanics and Equilibrium Thermodynamics, even though their presentations and derivations still differ essentially from author to author in logical structure and emphasis. Both Mechanics (Classical and Quantum) and Equilibrium Thermodynamics have been developed independently of one another for different applications and have enjoyed innumerable great successes. There are no doubts that the results of these theories will remain as milestones of the development of Science.

But as soon as they are confronted, Mechanics and Equilibrium Thermodynamics give rise to an apparent incompatibility of results: a dilemma, a paradox that has concerned generations of scientists during the last century and still remains unresolved. The problem arises when the general features of kinematics and dynamics in Mechanics are confronted with the general features of kinematics and dynamics implied by Equilibrium Thermodynamics. These features are in striking conflict in the two theories. The conflict concerns the notions of reversibility, availability of energy to adiabatic extraction, and existence of stable equilibrium states.^[1-2] Though perhaps presented with emphasis on other conflicting aspects, the apparent incompatibility of the theories of Mechanics and Equilibrium Thermodynamics is universally recognized by all scientists that have tackled the problem.^[3] What is not universally recognized is how to rationalize the paradoxical situation.^[1]

The attempt of rationalization better accepted within the physical community is offered by the theory of Statistical Mechanics. Like several other minor attempts of rationalization,^[1] Statistical Mechanics stems from the premise that Mechanics and Equilibrium Thermodynamics occupy different levels in the hierarchy of physical

theories: they both describe the same physical reality, but Mechanics (Quantum) is concerned with the true fundamental description, whereas Equilibrium Thermodynamics copes with the phenomenological description, in terms of a limited set of state variables, of systems with so many degrees of freedom that the fundamental quantum mechanical description would be overwhelmingly complicated and hardly reproducible.

When scrutinized in depth, the conceptual foundations of Statistical Mechanics are found to be shaky and unsound. For example, they seem to require that we abandon the concept of state of a system,^[4] a keystone of traditional physical thought. Nevertheless, in spite of the lack of a sound conceptual framework, the mathematical formalism and the results of Statistical Mechanics have enjoyed such great successes that the power of its methods have deeply convinced almost the entire physical community that the conceptual problems are indeed not there.

The formalism of Statistical Mechanics has also provided mathematical tools to attempt the extension of the results beyond the realm of thermodynamic equilibrium. In this area, the results have been successful in a variety of specific nonequilibrium problems. The many attempts to synthesize and generalize the results have generated important conclusions such as the Boltzmann equation, the Onsager reciprocity relations, the fluctuation-dissipation relations, and the Master equations. But, again, the vagueness of the conceptual foundations has forbidden so far the development of a sound theory of nonequilibrium.

The situation can be summarized as follows. On the one hand, the successes of Mechanics, Equilibrium Thermodynamics, and Statistical Mechanics both for equilibrium and nonequilibrium leave no doubts on the validity of their results. On the other hand, the need remains of a coherent physical theory capable of encompassing these same results within a sound conceptual unifying framework.

Of course, the vast majority of physicists would argue that there is no such need because there is no experimental observation that Statistical Mechanics cannot rationalize. But the problem at hand is not that there is a body of experimental evidence that cannot be regularized by current theories. Rather, it is that current theories have been developed and can be used only as ad-hoc working tools, successful to regularize the experimental evidence, but incapable to resolve conclusively the century-old fundamental questions on the physical roots of entropy and irreversibility.

In short, the irreversibility paradox and the dilemma on the meaning of entropy remain unresolved problems, aggravated by the more recent questions on the nature of nonequilibrium phenomena. The resolution of each of these questions requires consideration of all of them at once, because they are all intimately interrelated.

The notion of stability of equilibrium has played and will play a central role in the efforts to fill the gap. Of the two main schools of thought that during the past few decades have attempted frontal attacks to the problem, the Brussels school has emphasized the role of instability and bifurcations in self-organization of chemical and biological systems, and the MIT school has emphasized that the essence of the second law of Thermodynamics is a statement of existence and uniqueness of the stable equilibrium states of a system.

The recognition of the central role that stability plays in Thermodynamics^[5] is perhaps one of the most fundamental discoveries of the physics of the last three decades, for it has provided the key to a coherent resolution of the entropy-irreversibility-nonequilibrium dilemma that has kept in a state of tension the scientific community for longer than a century.

In this article, we first review the conceptual and mathematical framework of the problem; then, we discuss the role played by stability in guiding towards a coherent resolution; finally, we discuss the resolution offered by Quantum Thermodynamics.

2. BASIC CONCEPTUAL FRAMEWORK

Our objective in this section is to establish the basic conceptual framework in which both Mechanics and Equilibrium Thermodynamics are embedded. It involves the introduction of basic concepts that are traditional keystones of the kinematic and dynamic description in all physical theories. Specifically, we briefly review the concepts of constituent, system, property, state, equation of motion, process, reversibility, equilibrium, and stability of equilibrium.^[6]

The idea of a **constituent** of matter is used to denote a specific molecule, atom, ion, elementary particle, or field, that for a given description is to be considered as indivisible and structureless. The constituents are the elementary building blocks of a given level of description. It is clear that, for example, a specific molecule can be a constituent for the description of a certain class of phenomena, but for other phenomena its internal structure may not be ignored and, therefore, a different level of description must be chosen. The kind of physical laws we are concerned with are the most fundamental, i.e., those equally applicable at every level of description, such as the great conservation principles of Mechanics.

Kinematics

A **system** is a collection of constituents defined by the following specifications: (a) the type and the range of values of the **amount** of each constituent; (b) the type and the range of values of the **parameters** which fully characterize the **external** forces exerted on the constituents by bodies other than the constituents, for example, the parameters that describe the geometrical shape of a container; and (c) the **internal** forces between constituents such as the forces between molecules, the forces that promote or inhibit a chemical reaction, the partitions that separate constituents in one region of space from constituents in another region, or the interconnections between separated parts. Everything that is not included in the system is called the **environment** or the surroundings of the system.

At any instant of time, the values of the amounts of each type of constituent and the parameters of each external force do not suffice to characterize completely the condition of the system at that time. We need, in addition, the values of all the properties at the same instant of time. A **property** is an attribute that can be evaluated by means of a set of measurements and operations which are performed on the system and result in a value -- the **value of the property** -- independent of the measuring devices, other systems in the environment, and the history of the system. For example, the instantaneous position of a particular constituent is a property.

Some properties in a given set are **independent** if the value of each such property can be varied without affecting the value of any other property in the set. Other properties are not independent. For example, speed and kinetic energy of a molecule are not independent properties.

The values of the amounts of all the constituents, the values of all the parameters, and the values of a complete set of independent properties encompass all that can be said at an instant of time about a system and about the results of any measurement or observation that may be performed on the system at that instant of time. As such, the collection of all these values constitutes a complete characterization of the system at that instant of time. We call this characterization at an instant of time the **state** of the system.

Dynamics

The state of a system may change with time either spontaneously due to the internal dynamics of the system or as a result of interactions with other systems, or both. A system that can experience only spontaneous changes of state, i.e., a system that cannot induce any effects on the state of the environment, is called **isolated**. Systems that are not isolated can interact with each other in a number of different ways.

The relation that describes the evolution of the state of a system as a function of time is called the **equation of motion**.

In thermodynamics, the complete equation of motion is not known. For this reason, the description of a change of state is done in terms of the end states, i.e., the initial and the final states of the system, the modes of interaction that are active during the change of state, and conditions that have been established even without the complete knowledge of the equation of motion. Each mode of interaction is characterized by means of well-specified net flows of properties across the boundaries of the interacting systems. The conditions are consequences of the laws of thermodynamics which reflect facets of the equation of motion such as, specifically, the conditions that energy is conserved and entropy cannot be destroyed.

The end states and the modes of interaction associated with a change of state of a system are said to specify a **process**. Processes may be classified on the basis of the modes of interaction they involve. For example, a process that involves no interactions is called a **spontaneous process**. Again, a process that involves interactions that result in no external effects other than the change in height of a weight (or an equivalent mechanical effect) is called a **weight process**.

Another important classification of processes is in terms of the possibility of annulling all their effects. A process may be either reversible or irreversible. A process is **reversible** if there is a way to restore **both the system and its environment** to their respective initial states, i.e., if all the effects of the process can be annulled. A process is **irreversible** if there is no way to restore both the system and its environment to their respective initial states.

Types of States

Because the number of independent properties of a system is very large even for a system consisting of a single particle, and because most properties can vary over a large range of values, the number of possible states of a system is very large. To facilitate the discussion of these states, we find it useful to classify them into different categories with common features based on some criterion. In particular, we find that a classification of states according to their time evolution, i.e., according to the way each state changes as a function of time, brings forth many important aspects of physics.

We classify the states of a system into four types: unsteady, steady, nonequilibrium, and equilibrium. Moreover, we further classify equilibrium states into three types: unstable, metastable, and stable.

Unsteady is a state that changes as a function of time because of interactions of the system with other systems. **Steady** is a state that does not change as a function of time despite interactions of the system with other systems in the environment. **Nonequilibrium** is a state that changes spontaneously as a function of time, i.e., a state that evolves as time goes on without any effects on or interactions with any other systems. **Equilibrium** is a state that does not change as a function of time while the system is isolated -- a state that does not change spontaneously. **Unstable equilibrium** is an equilibrium state which, upon experiencing a minute and short lived influence by a system in the environment, proceeds from then on spontaneously to a sequence of entirely different states. **Metastable equilibrium** is an equilibrium state that may be changed to an entirely different state without leaving net effects in the environment of the system, but this can be done only by means of interactions which have a finite temporary effect on the state of the environment. **Stable equilibrium** is an equilibrium state that can be altered to a different state only by interactions that leave net effects in the environment of the system.

Starting either from a nonequilibrium or from an equilibrium state that is not stable, a system can be made to raise a weight without leaving any other net changes

in the state of the environment. In contrast, if we start from a stable equilibrium state such a raise of a weight is impossible. This impossibility is one of the consequences of the first law and the second law of thermodynamics.^[6]

3. BASIC MATHEMATICAL FRAMEWORK

The traditional structure of a physical theory is in terms of mathematical entities associated with each basic concept, and interrelations among such mathematical entities. In general, with the concept of **system** is associated a **metric space**. With the concept of **state** is associated an **element** of a subset of the metric space that we call the **state domain**. The different elements of the state domain represent all the different possible states of the system. With the concept of **property** is associated a **real functional** defined on the state domain. Different properties are represented by different real functionals, and the value of each property at a given state is given by the value of the corresponding functional evaluated at the element in the state domain representing the state. Some of the functionals representing properties of the system may depend also on the amounts of constituents and the parameters characterizing the external forces.

Quantum Mechanics

The metric space in Quantum Mechanics is a **Hilbert space** \mathcal{H} ($\dim \mathcal{H} \leq \infty$), the states are the elements ψ of \mathcal{H} , the properties are the real functionals of the form $\langle \psi, A\psi \rangle$ where $\langle \cdot, \cdot \rangle$ is the scalar product on \mathcal{H} and A some linear operator on \mathcal{H} . The composition of the system is embedded in the structure of the Hilbert space. Specifically,

$$\mathcal{H} = \mathcal{H}^1 \otimes \mathcal{H}^2 \otimes \dots \otimes \mathcal{H}^M \quad (1)$$

means that the system is composed of M distinguishable subsystems which may, for example, correspond to the different constituents. If the system is composed of a type of particle with amount variable over a range, then a functional on the Hilbert space represents the number of particles of that kind. The parameters characterizing the external forces may appear as external parameters in some property functionals. For example, the shape of a container is embedded in the position functionals as the contour outside which the functionals are identically null. The internal forces among constituents are embedded in the explicit form of the **Hamiltonian operator** H which gives rise to the energy functional $\langle \psi, H\psi \rangle$ and determines the dynamics of the system by means of the **Schrödinger equation of motion**

$$\frac{d\psi}{dt} = -\frac{i}{\hbar} H\psi \quad (2)$$

Because the solution of the Schrödinger equation can be written as

$$\psi(t) = U(t)\psi(0) \quad (3)$$

where $U(t)$ is the **unitary operator**

$$U(t) = \exp(-itH/\hbar) \quad (4)$$

it is standard jargon to say that the dynamics in Quantum Mechanics is unitary.

Statistical Mechanics

The formalism of Statistical Mechanics requires as metric space the space of all self-adjoint linear operators on \mathcal{H} , where \mathcal{H} is the same Hilbert space that Quantum Mechanics associates with the system. The "states" are the elements ρ in this metric space that are nonnegative-definite and unit-trace. We use quotation marks because in Statistical Mechanics these elements ρ , called the **density operators**, are interpreted as statistical indicators representing a statistical mixture of different "pure states" each of which would be represented by an idempotent density operator ρ , i.e., such that $\rho^2 = \rho$, so that ρ is a projection

operator, $\rho = P_\psi$, onto the one-dimensional linear span of some element ψ in \mathcal{H} and, as such, identifies a precise state of Quantum Mechanics. This interpretation, which summarizes perhaps too briefly the universally accepted interpretation of Statistical Mechanics, is indeed fraught with conceptual inconsistencies. For example, it starts with the premise that a system is always in one (possibly unknown) state, and then it implies as a logical consequence that a system may be at once in two or even more states:^[4] a self-inconsistency that mines the very essence of the notion of state of a system, a keystone of traditional physical thought. For lack of better, however, such inconsistencies are almost universally ignored, probably with the implicit motivation that "perhaps" the interpretation has some fundamental faults but the formalism is undoubtedly successful at regularizing data. So, let us summarize a few more points of this successful mathematical formalism.

The "states", "mixed" ($\rho^2 \neq \rho$) or "pure" ($\rho^2 = \rho$), are the self-adjoint, nonnegative-definite, unit-trace linear operators on \mathcal{H} . The "properties" are the real functionals defined on the "state" domain, for example, the functionals of the form $\text{Tr} A \rho$ where A is some linear operator on \mathcal{H} and Tr denotes the trace over \mathcal{H} .

The density operators that are so successful in modeling the stable equilibrium states of Thermodynamics have a mathematical expression that depends on the structure of the system. For a system with no structure such as a single particle system, the expression is

$$\rho = \exp(-\beta H) / \text{Tr} \exp(-\beta H) \quad (5)$$

where H is the Hamiltonian operator giving rise to the energy functional $\text{Tr} H \rho$ and β is a positive scalar. For a system with a variable amount of a single type of particle, the expression is

$$\rho = \exp(-\beta H - \nu N) / \text{Tr} \exp(-\beta H - \nu N) \quad (6)$$

where N is the number operator giving rise to the number-of-particle functional $\text{Tr} N \rho$ and ν is a scalar. For a system with n types of particles each with variable amount, the expression is

$$\rho = \exp(-\beta H - \sum_{i=1}^n \nu_i N_i) / \text{Tr} \exp(-\beta H - \sum_{i=1}^n \nu_i N_i) \quad (7)$$

If the system is composed of M distinguishable subsystems, each consisting of n types of particles with variable amounts, the structure is embedded in that of the Hilbert space (Equation 1) and in that of the Hamiltonian and the number operators

$$H = \sum_{J=1}^M H(J) \otimes I(\bar{J}) + V \quad (8)$$

$$N_i = \sum_{J=1}^M N_i(J) \otimes I(\bar{J}) \quad \text{for } i = 1, 2, \dots, n \quad (9)$$

where $H(J)$ denotes the Hamiltonian of the J -th subsystem when isolated, V denotes the interaction Hamiltonian among the M subsystems, $N_i(J)$ denotes the number-of-particles-of- i -th-type operator of the J -th subsystem, and $I(\bar{J})$ denotes the identity operator on the Hilbert space $\mathcal{H}^{\bar{J}}$ composed by the direct product of the Hilbert spaces of all subsystems except the J -th one, so that the Hilbert space of the overall system $\mathcal{H} = \mathcal{H}^J \otimes \mathcal{H}^{\bar{J}}$ and the identity operator $I = I(J) \otimes I(\bar{J})$.

The richness of this mathematical formalism goes well beyond the brief summary just reported. The results of Equilibrium Thermodynamics are all recovered with success and much greater detail if the thermodynamic entropy is represented by the functional

$$-k \text{Tr} \ln \rho \quad (10)$$

where k is the Boltzmann constant. The arguments that lead to this expression, and its well-known statistical interpretation within Statistical Mechanics need not be reported for they obviously suffer the same incurable conceptual disease as the

whole accepted interpretation of Statistical Mechanics. But the formalism works, and this is what counts to address our problem.

Unitary Dynamics

Remaining within Statistical Mechanics, the conceptual picture becomes more confused when the question of dynamics is brought in. Since a density operator ρ represents the "state" or rather the "statistical description" at one instant of time, how does it evolve in time? Starting with the (faulty) statistical interpretation, all books invariably report the "derivation" of the quantum equivalent of the Liouville equation, i.e., the von Neumann equation

$$\frac{d\rho}{dt} = -\frac{i}{\hbar}[H, \rho] \quad (11)$$

where $[H, \rho] = H\rho - \rho H$. The argument starts from the equation induced by the Schrödinger equation (Equation 2) on the projector $P_\psi = |\psi\rangle\langle\psi|$, i.e.,

$$\frac{dP_\psi}{dt} = -\frac{i}{\hbar}[H, P_\psi] \quad (12)$$

Then, the argument follows the interpretation of ρ as a statistical superposition of one-dimensional projectors such as $\rho = \sum_i w_i P_{\psi_i}$. The projectors P_{ψ_i} represent the endogenous description of the true but unknown state of the system and the statistical weights w_i represent the exogenous input of the statistical description. Thus, if each term P_{ψ_i} of the endogenous part of the description follows Equation 12 and the exogenous part is not changed, then the resulting overall descriptor ρ follows Equation 11.

Because the solutions of the von Neumann equation are just superpositions of solutions of the Schrödinger equation written in terms of the projectors, i.e., $P_\psi(t) = |\psi(t)\rangle\langle\psi(t)| = |U(t)\psi(0)\rangle\langle U(t)\psi(0)| = U(t)|\psi(0)\rangle\langle\psi(0)|U^\dagger(t) = U(t)P_\psi(0)U^{-1}(t)$, we have

$$\rho(t) = U(t)\rho(0)U^{-1}(t) \quad (13)$$

where $U^\dagger(t) = U^{-1}(t)$ is the adjoint of the unitary operator in Equation 4 which generates the endogenous quantum dynamics. It is again standard jargon to say that the dynamics of density operators is unitary.

The von Neumann equation or, equivalently, Equation 13, is a result almost universally accepted as an indispensable dogma. But we should recall that it is fraught with the same conceptual inconsistencies as the whole interpretation of Statistical Mechanics because its derivation hinges on such interpretation.

Based on the conclusion that the density operators evolve according to the von Neumann equation, the functional $-k \text{Tr}(\rho \ln \rho)$ and, therefore, the "entropy" is an invariant of the endogenous dynamics.

Here the problem becomes delicate. On the one hand, the "entropy" functional $-k \text{Tr}(\rho \ln \rho)$ is the key to the successful regularization of the results of Equilibrium Thermodynamics within the Statistical Mechanics formalism. Therefore, any proposal to represent the entropy by means of some new functional^[7] that increases with time under unitary dynamics is not acceptable unless it is also shown what relation the new functional bears with the entropy of Equilibrium Thermodynamics. On the other hand, the empirical fact that the thermodynamic entropy can increase spontaneously as a result of an irreversible process, is confronted with the invariance of the "entropy" functional $-k \text{Tr}(\rho \ln \rho)$ under unitary dynamics. This leads to the conclusion (within Statistical Mechanics) that entropy production by irreversibility cannot be a result of the endogenous dynamics and, hence, can only result from changes in time of the exogenous statistical description. We are left with the uncomfortable conclusion that entropy production by irreversibility is only a kind of statistical illusion.

4. IN SEARCH OF A BETTER THEORY

For a variety of reasons -- statistical, phenomenological, thermodynamic, information-theoretic, quantum-theoretic, conceptual -- many investigators have concluded that the von Neumann equation of motion (Equation 11) is incomplete, and a number of modifications have been attempted.^[8] However, the underlying conceptual framework has invariably remained that of Statistical Mechanics and, thus, the attempts have either failed or remained as ad-hoc tools valid only for the description of specific problems such as the nonequilibrium dynamics of laser systems. Indeed, within the framework of Statistical Mechanics a modification of the von Neumann equation could be justified only as a way to describe the exogenous dynamics of the statistical weights, but this does not remove the conceptual inconsistencies.

The Brussels school has recently tried a different approach.^[7] That of constructing a functional for the entropy, different from $-k \text{Tr} \rho \ln \rho$, that would be increasing in time under the unitary dynamics generated by the von Neumann equation. The way this is done is by introducing a new "state" $\tilde{\rho}$ obtained from the usual density operator ρ by means of a transformation, $\tilde{\rho} = \Lambda^{-1}(L)\rho$, where $\Lambda^{-1}(L)$ is a superoperator on the Hilbert space \mathcal{H} of the system defined as a function of the Liouville superoperator $L \cdot = [H, \cdot]/\hbar$ and such that the von Neumann equation for ρ , $d\rho/dt = -iL\rho$, induces an equation of motion for $\tilde{\rho}$, $d\tilde{\rho}/dt = -i\Lambda^{-1}(L)L\Lambda(L)\tilde{\rho}$, such that the new "entropy" functional $-k \text{Tr} \tilde{\rho} \ln \tilde{\rho}$ is increasing with time. Formally, once the old "state" ρ is substituted with the new "state" $\tilde{\rho}$, this approach seems tantamount to an attempt to modify the von Neumann equation, capable therefore only to describe the exogenous dynamics of the statistical description but not to unify Mechanics and Equilibrium Thermodynamics any better than done by Statistical Mechanics.

However, the language used by the Brussels school in presenting this new approach has gradually adopted during the last decade a new important element with growing conviction: the idea that entropy is a microscopic quantity and that irreversibility should be incorporated in the microscopic description. Credit for this new and revolutionary idea, as well as its first adoption and coherent implementation, must be given to the pioneers of the MIT school,^[9] even though the Brussels school might have reached this conclusion through an independent line of thought. This is shown by the quite different developments the idea has produced in the two schools.

As we will see, the implementation proposed by the MIT school has provided for the first time an alternative to Statistical Mechanics capable of retaining all the successful aspects of its formalism within a sound conceptual framework free of inconsistencies and drastic departures from the traditional structure of a physical theory.

5. THE NEW QUANTUM KINEMATICS

In their effort to implement the idea that entropy is a microscopic, nonstatistical property of matter in the same sense as energy is a microscopic, nonstatistical property, Hatsopoulos and Gyftopoulos^[9] concluded that the state domain of Quantum Mechanics is too small to include all the states that a physical system can assume. Indeed, the entire body of results of Quantum Mechanics has been so successful in describing empirical data that it must be retained as a whole. A theory that includes also the results of Equilibrium Thermodynamics and the successful part of the formalism of Statistical Mechanics must necessarily be an augmentation of Quantum Mechanics, a theory in which Quantum Mechanics is only a subcase.

Next came the observation that all the successes of the formalism of Statistical Mechanics based on the density operators ρ are indeed independent of their statistical

interpretation. In other words, all that matters is to retain the formalism and construct a new consistent interpretation.

The great discovery was that all this can be achieved if we admit that **physical systems have access to many more states than those described by Quantum Mechanics** and that the set of states is in one-to-one correspondence with the set of self-adjoint, nonnegative-definite, unit-trace linear operators ρ on the same Hilbert space \mathcal{H} that Quantum Mechanics associates with the system. Figure 1 gives a pictorial idea of the augmentation of the state domain implied by the Hatsopoulos-Gyftopoulos kinematics. The states considered in Quantum Mechanics are only the extreme points of the set of states a system really admits.

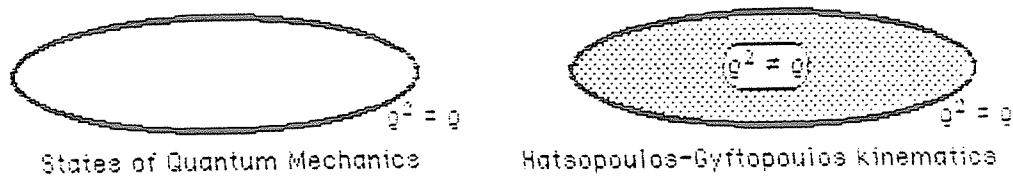


Figure 1

In terms of interpretation, the conceptual inconsistencies inherent in Statistical Mechanics are removed. The **state operators** ρ are mathematically identical to the density operators of Statistical Mechanics, but now they represent true states, in exactly the same way as a state vector ψ represents a true state in Quantum Mechanics. Statistics plays no more role, and a linear decomposition of an operator ρ has no more physical meaning than a linear decomposition of a vector ψ in Quantum Mechanics or a Fourier expansion of a function. Monsters that are simultaneously in two or more different states are removed together with the exogenous statistics. The traditional concept of state of a system is saved.

Of course, one of the most revolutionary ideas introduced by Quantum Mechanics has been the existence, within the individual state of any system, of an indeterminacy resulting in irreducible dispersions of measurement results. This indeterminacy (Heisenberg uncertainty principle) is embedded in the mathematical structure of Quantum Mechanics and is fully contained in the description of states by means of vectors ψ in a Hilbert space. The indeterminacy is not removed by the augmentation of the state domain to include all the state operators ρ . Rather, a second level of indeterminacy is added for states that are not mechanical, i.e., states such that $\rho^2 \neq \rho$. Entropy, represented by the functional $-k \text{Tr}(\rho \ln \rho)$, can now be interpreted as a measure of the breadth of this additional indeterminacy, which is exactly as fundamental and irreducible as the Heisenberg indeterminacy.

6. THE ROLE OF STABILITY

The richness of the new augmented kinematics guarantees enough room for the resolution of the many questions that must be addressed in order to complete the theory and accomplish the necessary unification. Among the questions, the first is whether the second law of thermodynamics can be part of the new theory without having to resort to statistical, phenomenological or information-theoretic arguments.

The second law is a statement of existence and uniqueness of the stable equilibrium states for each set of values of the energy functional, the number-of-particle functionals and the parameters.^[5-6] Adjoining this statement to the structure of the new kinematics leads to identify explicitly the state operators representing the stable equilibrium states and to prove that only the functional $-k \text{Tr}(\rho \ln \rho)$ can represent the thermodynamic entropy.^[9] Mathematically, the states of Equilibrium Thermodynamics are represented by exactly the same operators as in

Statistical Mechanics (Equations 5 to 7). Thus, the theory bridges the gap between Mechanics and Equilibrium Thermodynamics.

Among all the states to which a system has access, those of Mechanics are represented by the idempotent state operators and those of Equilibrium Thermodynamics by operators of the form of Equations 5 to 7 depending on the structure of the system. Thus, the state domain of Mechanics and the state domain of Equilibrium Thermodynamics are only two very small subsets of the entire state domain of the system.

The role of stability goes far beyond the very important result just cited, namely, the unification of Mechanics and Thermodynamics within a single uncontradictory structure that retains without modification all the successful mathematical results of Mechanics, Equilibrium Thermodynamics, and Statistical Mechanics. It provides further key guidance in addressing the question of dynamics.

The question is as follows. According to the new kinematics a system has access to many more states than those contemplated by Quantum Mechanics. The states of Quantum Mechanics evolve in time according to the Schrödinger equation of motion, which can be written either as Equation 2 or as Equation 12. But how do all the other states evolve in time? Such states are beyond the realm of Quantum Mechanics and, therefore, we cannot expect to derive their time evolution from that of Mechanics. We have to find a dynamical law for these states. In view of the breadth of the set of states in the augmented kinematics, the problem may seem at first sight extremely open to all sorts of different approaches. But, on the contrary, it is very much delimited by a number of restrictive constraints imposed by the many conditions that such a general dynamical law must satisfy. Among these conditions, we will see that the most restrictive are those related to the stability of the states of Equilibrium Thermodynamics.

Conditions for a General Dynamical Law

Our goal is to construct a theory that retains as much as possible of the traditional conceptual keystones of a physical theory. For example, we have saved the concept of state of a system. Now we intend to save the principle of causality, by which future states of an isolated system should unfold deterministically from initial states along smooth unique trajectories in the state domain. Given the state at one instant of time, the future as well as the past should always be predictable, at least in principle.

We see no reason to conclude that:^[10] "The deterministic laws of physics, which were at one point the only acceptable laws, today seem like gross simplifications, nearly a caricature of evolution." The observation that:^[11] "for any dynamical system we never know the exact initial conditions and therefore the trajectory" is not sufficient reason to discard the concept of trajectory. The principle of causality and the traditional concept of trajectory can coexist very well with all the interesting observations by the Brussels school on the relation between organization and coherent structures in chemical, biological, and fluid systems and bifurcations born of singularities and nonlinearities of the dynamical laws. A clear example is given by the dynamical laws of fluid mechanics, which are deterministic, obey the principle of causality, and yet can give rise to beautifully organized and coherent vortex structures.

Coming back to the conditions that must be satisfied by a general dynamical law, we list below the most important.

Condition I

The states of Quantum Mechanics must evolve according to the Schrödinger equation of motion. Therefore, the trajectories passing through any state q such that $q^2 = q$ must be entirely contained in the state domain of Quantum Mechanics, i. e., the condition $q^2 = q$ must be satisfied along the entire trajectory. This also means that no trajectory can enter or leave the state domain of Quantum Mechanics. In view

of the fact that the states of Quantum Mechanics are the extreme points of our augmented state domain, the trajectories of Quantum Mechanics must be boundary solutions of the dynamical law. By continuity, there must be trajectories that approach indefinitely these boundary solutions either as $t \rightarrow -\infty$ or as $t \rightarrow +\infty$. Thus, the periodic trajectories of Quantum Mechanics should emerge as boundary limit cycles of the complete dynamics.

Condition 2

If the system is isolated, the value of the energy functional $\text{Tr}H\rho$ must remain invariant along every trajectory. If the isolated system consists of a variable amount of a single type of particle with a number operator N that commutes with the Hamiltonian operator H , then also the value of the number-of-particle functional $\text{Tr}N\rho$ must remain invariant along every trajectory. If the isolated system consist of n types of particles each with variable amount and each with a number operator N_i that commutes with the Hamiltonian H , then also the value of each number-of-particle functional $\text{Tr}N_i\rho$ must remain invariant along every trajectory.

Condition 3

For an isolated system composed of two subsystems A and B with associated Hilbert spaces \mathcal{H}^A and \mathcal{H}^B , so that the Hilbert space of the system is $\mathcal{H} = \mathcal{H}^A \otimes \mathcal{H}^B$, if the two subsystems are noninteracting, i.e., the Hamiltonian operator $H = H_A \otimes I_B + I_A \otimes H_B$, then the functionals $\text{Tr}(H_A \otimes I_B)\rho$ and $\text{Tr}(I_A \otimes H_B)\rho$ represent the energies of the two subsystems and must remain invariant along every trajectory.

Condition 4

Two subsystems A and B are in independent states if the state operator $\rho = \rho_A \otimes \rho_B$, where $\rho_A = \text{Tr}_B \rho$, $\rho_B = \text{Tr}_A \rho$, Tr_B denotes the partial trace over \mathcal{H}^B and Tr_A the partial trace over \mathcal{H}^A . For noninteracting subsystems, every trajectory passing through a state in which the subsystem are in independent states must maintain the subsystems in independent states along the entire trajectory. This condition guarantees that when two uncorrelated systems do not interact with each other, each evolves in time independently of the other.

Condition 5

A state operator ρ represents an equilibrium state if $d\rho/dt = 0$. For each given set of feasible values of the energy functional $\text{Tr}H\rho$ and the number-of-particle functionals $\text{Tr}N_i\rho$ (i.e., the functionals that must remain invariant according to Condition 2 above), among all the equilibrium states that the dynamical law may admit there must be one and only one which is globally stable (definition below). This stable equilibrium state must represent the corresponding state of Equilibrium Thermodynamics and, therefore, must be of the form given by Equations 5 to 7. All the other equilibrium states that the dynamical law may admit must not be globally stable.

Condition 6

The principle of nondecrease of entropy must be satisfied, i.e., the rate of change of the entropy functional $-k\text{Tr}\rho \ln \rho$ along every trajectory must be nonnegative.

It is clear that with all these constraints the problem of finding the complete dynamical law is not at all open to much arbitrariness.

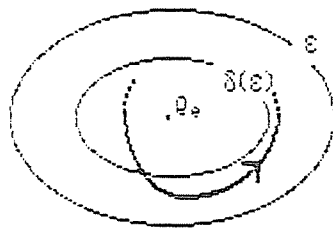
The condition concerning the stability of the thermodynamic equilibrium states is extremely restrictive and requires further discussion.

Lyapunov Stability in Thermodynamics

In order to implement Condition 5 above, we need to establish the relation between the notion of stability implied by the second law of Thermodynamics^{[5][9]} and the mathematical concept of stability. An equilibrium state is stable in the sense required by the second law if it can be altered to a different state only by interactions

that leave net effects in the state of the environment. We will call this notion of stability **global stability**. The notion of stability according to Lyapunov will be called **local stability**.

Let us denote the trajectories generated by the dynamical law on our state domain by $u(t, \rho)$, i.e., $u(t, \rho)$ denotes the state at time t along the trajectory passing through state ρ at time $t = 0$. A state ρ_e is an equilibrium state if and only if $u(t, \rho_e) = \rho_e$ for all times t . An equilibrium state ρ_e is **locally stable (according to Lyapunov)** if and only if for every $\varepsilon > 0$ there is a $\delta(\varepsilon) > 0$ such that $d(\rho, \rho_e) < \delta(\varepsilon)$ implies $d(u(t, \rho), \rho_e) < \varepsilon$ for all $t > 0$ and every ρ , i.e., such that every trajectory that passes within the distance $\delta(\varepsilon)$ from state ρ_e proceeds in time without ever exceeding the distance ε from ρ_e (Figure 2). Conversely, an equilibrium state ρ_e is **unstable** if and only if it is not locally stable, i.e., there is an $\varepsilon > 0$ such that for every $\delta > 0$ there is a trajectory passing within distance δ from ρ_e and reaching at some later time farther than the distance ε from ρ_e (Figure 3).



Locally stable equilibrium

Figure 2

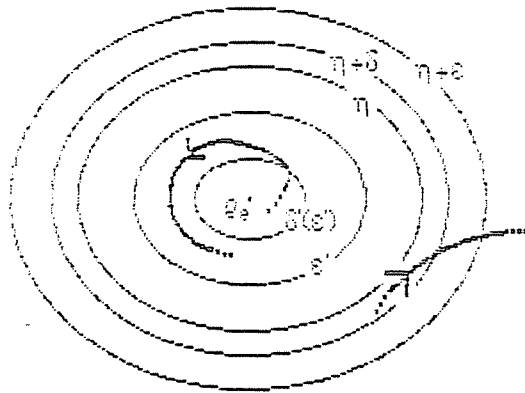


Unstable equilibrium

Figure 3

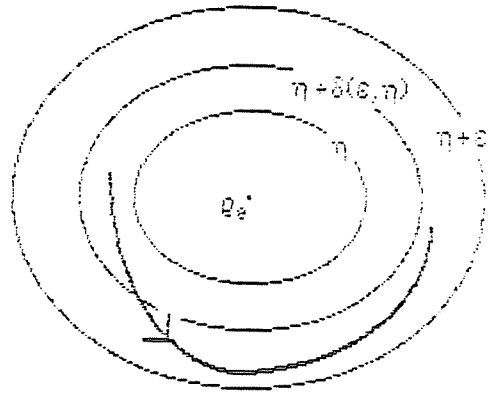
The Lyapunov concept of instability of equilibrium is clearly equivalent to that of instability stated in Thermodynamics according to which an equilibrium state is unstable if, upon experiencing a minute and short lived influence by some system in the environment (i.e., just enough to take it from state ρ_e to a neighboring state at infinitesimal distance δ), proceeds from then on spontaneously to a sequence of entirely different states (i.e., farther than some finite distance ε).

It follows that the concept of stability in Thermodynamics implies that of Lyapunov local stability. However, it is stronger because it also excludes the concept of **metastability**. Namely, the states of Equilibrium Thermodynamics are **global** stable equilibrium states in the sense that not only they are locally stable but they cannot be altered to entirely different states even by means of interactions which leave temporary but finite effects in the environment. Mathematically, the concept of metastability can be defined as follows. An equilibrium state ρ_e is **metastable** if and only if it is locally stable but there is an $\eta > 0$ and an $\varepsilon > 0$ such that for every $\delta > 0$ there is a trajectory $u(t, \rho)$ passing at $t = 0$ between distance η and $\eta + \delta$ from ρ_e , $\eta < d(u(0, \rho), \rho_e) < \eta + \delta$, and reaching at some later time $t > 0$ a distance farther than $\eta + \varepsilon$, $d(u(t, \rho), \rho_e) \geq \eta + \varepsilon$ (Figure 4). Thus, the concept of global stability implied by the second law is as follows. An equilibrium state ρ_e is **globally stable** if for every $\eta > 0$ and every $\varepsilon > 0$ there is a $\delta(\varepsilon, \eta) > 0$ such that every trajectory $u(t, \rho)$ with $\eta < d(u(0, \rho), \rho_e) < \eta + \delta(\varepsilon, \eta)$, i.e., passing at time $t = 0$ between distance η and $\eta + \delta$ from ρ_e , remains with $d(u(t, \rho), \rho_e) < \eta + \varepsilon$ for every $t > 0$, i.e., proceeds in time without ever exceeding the distance $\eta + \varepsilon$ (Figure 5).



Metastable equilibrium

Figure 4



Globally stable equilibrium

Figure 5

The second law requires that for each set of values of the invariants $\text{Tr}H\rho$ and $\text{Tr}N_i\rho$ (as many as required by the structure of the system), and of the parameters describing the external forces (such as the size of a container), there is one and only one globally stable equilibrium state. Thus, the dynamical law may admit many equilibrium states that all share the same values of the invariants and the parameters, but among all these only one must be globally stable, i.e., all the other equilibrium states must be either unstable or metastable.

For example, we may use this condition to show that a unitary (Hamiltonian) dynamical law would be inconsistent with the second-law stability requirement. A unitary dynamical law in our augmented kinematics would be expressed by an equation of motion formally identical to Equation 11 with solutions given by Equation 13 and trajectories $u(t, \rho) = U(t)\rho(0)U^{-1}(t)$ with $U(t) = \exp(-itH/\hbar)$. Such a dynamical law would admit as equilibrium states all the states ρ_e such that $\rho_e H = H\rho_e$. Of these states there are more than just one for each set of values of the invariants. With respect to the metric $d(\rho_1, \rho_2) = \text{Tr}|\rho_1 - \rho_2|$, it is easy to show^[12] that every trajectory $u(t, \rho)$ would be equidistant from every equilibrium state ρ_e , i.e., $d(u(t, \rho), \rho_e) = d(u(0, \rho), \rho_e)$ for all t and all ρ . Therefore, all the equilibrium states would be globally stable and there would be more than just one for each set of values of the invariants, thus violating the second-law requirement.

The entropy functional $-k\text{Tr}\rho \ln \rho$ plays a useful role in proving the stability of the states of Equilibrium Thermodynamics (Equations 5 to 7) provided the dynamical law guarantees that $-k\text{Tr}u(t, \rho) \ln u(t, \rho) \geq -k\text{Tr}\rho \ln \rho$ for every trajectory, i.e., provided Condition 6 above is satisfied. The proof of this is nontrivial and is given in Ref. 12 where, however, we also show that the entropy functional, contrary to what repeatedly emphasized by the Brussels school, is **not** a Lyapunov function, even if, in a strict sense^[12] that depends on the continuity and the conditional stability of the states of Equilibrium Thermodynamics, it does provide a criterion for the stability of these states. Anyway, the statement that the second law^[13] "can be formulated as a dynamical principle in terms of the existence of a Lyapunov variable" would be incorrect even if the entropy were a Lyapunov variable, because this would suffice only to guarantee the stability of the states of Equilibrium Thermodynamics but **not** to guarantee, as required by the second law, the instability or metastability of all the other equilibrium states.

7. THE DYNAMICAL LAW OF QUANTUM THERMODYNAMICS

The efforts devoted by the MIT group during the last twenty years to construct a theory that within a single uncontradictory nonstatistical structure would resolve all the fundamental questions raised so far in our discussion, culminated with the formulation of a theory that we call Quantum Thermodynamics. We have already discussed the kinematics adopted within Quantum Thermodynamics, namely, that proposed by Hatsopoulos and Gyftopoulos to resolve the inconsistencies of Statistical Mechanics and to achieve a nonstatistical rationalization of Mechanics and Equilibrium Thermodynamics.

Let us summarize briefly the elements of Quantum Thermodynamics that we have already discussed. With every system is associated a Hilbert space \mathcal{H} , the **same** \mathcal{H} that is associated with the system in Quantum Mechanics. The composition of the system in terms of distinguishable subsystems is reflected by the structure of the Hilbert space \mathcal{H} as a direct product of subspaces. The subdivision into **constituents**, considered as indivisible and structureless, is particularly important because it defines the **level of description** of the system and specifies its elementary structure. This will determine also the structure of the dynamical law.

With the state of the system is associated a **state operator** ρ , i.e., a self-adjoint, nonnegative-definite, unit-trace linear operator on \mathcal{H} . If the state operator is idempotent, i.e., $\rho^2 = \rho$, then ρ is a one-dimensional projector onto the linear span of some vector ψ in \mathcal{H} , i.e., $\rho = P_\psi$, and corresponds to a **mechanical state**, i.e., a state of Quantum Mechanics. If ρ is not idempotent then it corresponds to a **nonmechanical state**, i.e., a state not contemplated by Quantum Mechanics. Again, we emphasize that a unique and key premise of Quantum Thermodynamics is that in addition to the states of Quantum Mechanics a system (even if strictly uncorrelated and isolated from the rest of the universe) has access also to states that must be described by nonidempotent state operators. Among these nonmechanical states are, for example, those expressed in terms of functions of the Hamiltonian and number-of-particle operators in Equations 5 to 7.

The real functional representing the **entropy** is $-k \text{Tr} \rho \ln \rho$. It represents a property of matter in the same sense as the energy functional represents a property of matter. Entropy can be interpreted as a measure of the breadth of the irreducible indeterminacy inherent in the states represented by nonidempotent state operators. This indeterminacy is added on top of that implied by the Heisenberg uncertainty principle, and is responsible, for example, of the impossibility of adiabatic extraction of energy from the states of Equilibrium Thermodynamics (impossibility of perpetual motion of the second kind).

If a constituent is part of a system with other constituents, its state may be correlated or uncorrelated from the rest of the system. Considering a system composed of M distinguishable constituents, the Hilbert space $\mathcal{H} = \mathcal{H}^1 \otimes \mathcal{H}^2 \otimes \dots \otimes \mathcal{H}^M$ where \mathcal{H}^J is the Hilbert space that would be associated with the J -th constituent were it the only constituent of the system, and $\mathcal{H}^{\bar{J}}$ that associated with the rest of the system. We say that constituent J is uncorrelated from the rest of the system if the state operator $\rho = \rho_J \otimes \rho_{\bar{J}}$ where $\rho_J = \text{Tr}_{\bar{J}} \rho$ and $\rho_{\bar{J}} = \text{Tr}_J \rho$, $\text{Tr}_{\bar{J}}$ denotes the partial trace over $\mathcal{H}^{\bar{J}}$ and Tr_J the partial trace over \mathcal{H}^J .

The most general way to represent a constituent is in terms of a **field** consisting of variable amounts of all the n types of particles present in the overall system. For the J -th constituent considered as isolated, we denote the Hamiltonian operator on \mathcal{H}^J by $H(J)$, the number-of-particles-of- i -th-type operator by $N_i(J)$ and the identity operator by $I(J)$. The Hamiltonian H of the overall system, including the interaction term, is given by Equation 8 and the overall-number-of-particles-of- i -th-type operator N_i by Equation 9. To simplify the notation, and without loss of generality, we assume that all the constituents of the system are of this general

kind. Then, for example, we can specify that, say, the K-th constituent consists of only the 4-th type of particle with variable amount by imposing that $N_i(K)$ is the null operator for every $i \neq 4$. Again, if the K-th constituent consists of only the 2-nd type of particle with a fixed amount, say, 5 particles, then $N_i(K) = 0$ for $i \neq 2$ and $N_2(K) = 5 I(K)$.

The dynamical law proposed by the present author to complete Quantum Thermodynamics is given by the following general equation of motion, which satisfies all the Conditions 1 to 6 listed above,

$$\frac{d\rho}{dt} = -\frac{i}{\hbar} [H, \rho] - \sum_{J=1}^M \frac{1}{\tau_J} \frac{1}{2} [\sqrt{\rho_J} D_J + (\sqrt{\rho_J} D_J)^\dagger] \otimes \rho_J \quad (14)$$

where τ_J is a positive internal-dissipation time for constituent J, X^\dagger denotes the adjoint of operator X, and the operators D_J are defined as follows

$$D_J = \sqrt{\rho_J} (B \ln \rho)^J - (\sqrt{\rho_J} (B \ln \rho)^J)_L [\sqrt{\rho_J}, \sqrt{\rho_J} (H)^J, \sqrt{\rho_J} N_1(J), \dots, \sqrt{\rho_J} N_n(J)] \quad (15)$$

where

$$(B \ln \rho)^J = \text{Tr}_J [(I(J) \otimes \rho_J) B \ln \rho] \quad (16)$$

$$(H)^J = \text{Tr}_J [(I(J) \otimes \rho_J) H] \quad (17)$$

and

$$(\sqrt{\rho_J} (B \ln \rho)^J)_L [\sqrt{\rho_J}, \sqrt{\rho_J} (H)^J, \sqrt{\rho_J} N_1(J), \dots, \sqrt{\rho_J} N_n(J)] \quad (18)$$

denotes the orthogonal projection of operator $\sqrt{\rho_J} (B \ln \rho)^J$ onto the linear span of operators $\sqrt{\rho_J}, \sqrt{\rho_J} (H)^J, \sqrt{\rho_J} N_1(J), \dots, \sqrt{\rho_J} N_n(J)$ with respect to the scalar product on the set of linear operators on \mathcal{H}^J defined by $(F, G) = \frac{1}{2} \text{Tr}_J (F^\dagger G + G^\dagger F)$. Operator B is the idempotent operator obtained from ρ by substituting each nonzero eigenvalue of ρ with unity, so that $\text{Tr} B$ equals the number of nonzero eigenvalues of ρ and $B \ln \rho$ is a well-defined operator with eigenvalues that equal either zero or the logarithm of the nonzero eigenvalues of ρ .

Equation 14 is well-defined over the entire state domain. More explicit expressions of the operators D_J are given in Ref. 14 where, among many other results, it is shown that indeed Conditions 1 to 6 are satisfied. The mathematics may seem involved and ad-hoc, but its geometrical and physical interpretation is simple and appealing (Figure 6).

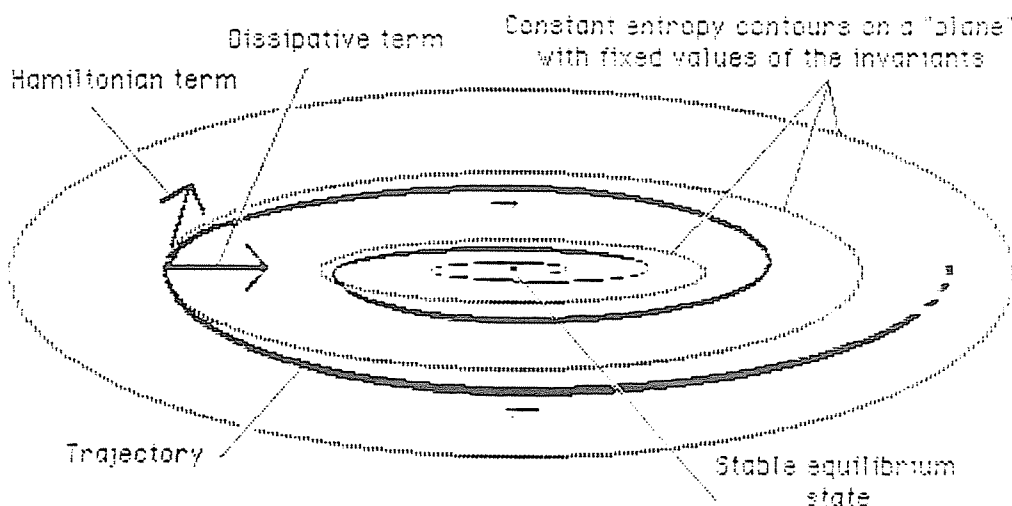


Figure 6

We call the first term in the right-hand side of Equation 14 the **Hamiltonian term** and the second term the **dissipative term**. The Hamiltonian term of the

equation of motion tends to generate a reversible unitary evolution which, as we know, would maintain the trajectory on a constant entropy surface in the state domain. The dissipative term tends to generate an irreversible evolution by "pulling" the state operator towards the local direction of steepest entropy ascent compatible with the conditions on the time invariants and the structure of the system. In view of its nonlinearity in the state operator ρ , the "strength" of the dissipative term depends not only on the internal-dissipation time τ_J but most importantly on the instantaneous location of the state operator in the state domain. The actual evolution results from the competition of the Hamiltonian and the dissipative terms.

For a system consisting of a single constituent, the equation of motion is clearly simplified. Then, the dissipative term pulls the state ρ exactly in the direction of steepest ascent of $-k \text{Tr} \rho \ln \rho$ compatible with the invariance of $\text{Tr} \rho$, $\text{Tr} \rho N_i$ and $\text{Tr} \rho H$.

For a system with many constituents, the structure of the dissipative term is such that each constituent contributes its own internal tendency towards its own "perception" of the direction of steepest entropy ascent, namely, the direction of highest increase of the functional $-k \text{Tr}_J \rho_J (\text{Bl} \rho_J)^J$ compatible with the conditions of invariance of the functionals $\text{Tr}_J \rho_J$, $\text{Tr}_J \rho_J N_i(J)$, and $\text{Tr}_J \rho_J (H)^J$. In this sense, the functionals $\text{Tr}_J \rho_J (H)^J$ and $-k \text{Tr}_J \rho_J (\text{Bl} \rho_J)^J$ represent a sort of "internal perception" by the J -th constituent of the overall energy and entropy of the system.

The explicit form of the equation for a single constituent consisting of a single two-level atom or spin is discussed in Ref. 15. In Ref. 16 we also attempted to establish corrections implied by our equation of motion onto some basic quantum-electrodynamic results on resonance fluorescence and stimulated emission.

The nonlinearity of the dissipative term and the singularity of operator $\text{Bl} \rho$ guarantee at the level of the individual dynamics of each constituent of matter a great richness of dynamical features which, together with the complexity of structure for a system with many distinguishable constituents, can certainly produce the wealth of nonequilibrium conditions and self-organization behavior sought by the Brussels school.

8. NONEQUILIBRIUM AND ONSAGER RECIPROCALITY

Another important question that is resolved by Quantum Thermodynamics is related to the general description of nonequilibrium states and their time evolution. We have seen that the states of Quantum Mechanics and those of Equilibrium Thermodynamics are only very small subsets of the state domain of Quantum Thermodynamics. With the exception of a relatively small number of equilibrium states that are not globally stable,^[14] all the other states are nonequilibrium.

An interesting way to represent a general state operator, equilibrium or nonequilibrium, is in terms of a fixed set of operators $X_1, X_2, \dots, X_i, \dots$ that **span** the real space of self-adjoint linear operators on \mathcal{H} . We can write any state operator as^[17]

$$\rho = B \exp\left(-\sum_i f_i X_i\right) \quad (19)$$

where $f_1, f_2, \dots, f_i, \dots$ are real scalars and B is an idempotent self-adjoint operator. The main and most important difference between Equation 19 and Equations 5 to 7 is that the list of operators X_i must be **complete** in the sense that any other self-adjoint operator on \mathcal{H} can be expressed as a linear combination of the X_i 's. For example, if $\dim \mathcal{H} = \infty$ then the list of X_i 's is also infinite. However, it may be possible to judiciously select the set of X_i 's so that, for states that are close enough to the stable equilibrium states of Equations 5 to 7, most of the scalars f_i are

practically zero. Then, for this special set of states, the summation in Equation 19 can be approximated by a finite summation over a limited set of relevant X_i 's.

In terms of Equation 19, the entropy functional becomes a linear combination of the functionals $\text{Tr}X_{i\rho}$, i. e.,

$$-k \text{Tr} \rho \ln \rho = k \sum_i f_i \text{Tr} X_{i\rho} \quad (20)$$

so that the scalar f_i can be interpreted as a **generalized "affinity"** or **"force"** representing the marginal dependence of the entropy functional on the change in value of the property represented by functional $\text{Tr}X_{i\rho}$, in the neighborhood of the given state ρ .

It is then interesting to evaluate the rate of change of $\text{Tr}X_{i\rho}$ as due to the equation of motion (Equation 14), specifically, to the dissipative term of the equation of motion. We know that the Hamiltonian term cannot alter the value of the entropy. Therefore, we focus our attention on the contribution of the dissipative term, that we denote by DX_i/Dt and call the **dissipative rate of change** of the property represented by the functional $\text{Tr}X_{i\rho}$.

Substituting the explicit expression of the dissipative term,^[17] we find

$$\frac{DX_i}{Dt} = \sum_j f_j L_{ij}(\rho) \quad (21)$$

and

$$-\frac{d}{dt} k \text{Tr} \rho \ln \rho = k \sum_i f_i \frac{DX_i}{Dt} = \sum_i \sum_j f_i f_j L_{ij}(\rho) \quad (22)$$

where

$$\begin{aligned} L_{ij}(\rho) &= \sum_{J=1}^M \frac{1}{\tau_J} \left([\sqrt{\rho_J}(X_i)^\nu - (\sqrt{\rho_J}(X_i)^\nu)_L], [\sqrt{\rho_J}(X_j)^\nu - (\sqrt{\rho_J}(X_j)^\nu)_L] \right) \\ &= L_{ji}(\rho) \end{aligned} \quad (23)$$

$$(X_i)^\nu = \text{Tr}_J [(I(J) \otimes \rho_J) X_i] \quad (24)$$

(\cdot, \cdot) denotes the scalar product on the set of linear operators on \mathcal{X}^ν defined by $(F, G) = \frac{1}{2} \text{Tr}_J (F^*G + G^*F)$, and $(\sqrt{\rho_J}(X_i)^\nu)_L$ denotes the orthogonal projection of operator $\sqrt{\rho_J}(X_i)^\nu$ onto the linear span of operators $\sqrt{\rho_J}, \sqrt{\rho_J}(H)^\nu, \sqrt{\rho_J}N_1(J), \dots, \sqrt{\rho_J}N_n(J)$.

In view of Equation 21, the functional $L_{ij}(\rho)$ can be interpreted as a **generalized "conductivity"** expressing the linear dependence of the dissipative rate of change of the i -th functional $\text{Tr}X_{i\rho}$ on the j -th affinity f_j . The conclusion that $L_{ij}(\rho) = L_{ji}(\rho)$, implies that at every state ρ , the marginal dependence of the dissipative rate of change of the i -th functional $\text{Tr}X_{i\rho}$ on changes in value of the j -th affinity f_j is equal to the marginal dependence of the dissipative rate of change of the j -th functional $\text{Tr}X_{j\rho}$ on changes in value of the i -th affinity f_i . This conclusion represents a proof of Onsager's reciprocity relations^[18] expressing the reciprocity of the mutual interrelations between different irreversible rate phenomena simultaneously occurring at a nonequilibrium state.

Onsager's result was obtained from empirical observations on nonequilibrium phenomena very close to stable thermodynamic equilibrium, so that the list of X_i 's was indeed very short, and the result valid only for a limited class of states. Our result^[17] generalizes the validity of Onsager's reciprocity relations to all nonequilibrium states, close and far from stable thermodynamic equilibrium. Of course, the price we have to pay to describe nonequilibrium states far from stable equilibrium is that we **must** use a much larger, possibly infinite list of X_i 's.

We conclude by reemphasizing that all the results summarized in this article unfold from the recognition of the role played by stability in Thermodynamics.^[5]

6][9][12][14] In our view, Quantum Thermodynamics constitutes the first self-consistent and conceptually-sound resolution of the century-old dilemma on the nature of entropy and irreversibility. While encompassing all the successful results of Quantum Mechanics, Equilibrium Thermodynamics, and the formalism of Statistical Mechanics, it opens new vistas towards a unifying reexamination of nonequilibrium phenomena.

ACKNOWLEDGEMENT

Financial support of the Thermo Electron Corporation is gratefully acknowledged.

REFERENCES

1. J.L. Perk and R.F. Simmons jr., in *Old and New Questions in Physics, Cosmology, Philosophy, and Theoretical Biology*, A. van der Merwe, Editor, Plenum Press, N.Y., 1983.
2. G.P. Beretta, in *Frontiers of Nonequilibrium Statistical Physics*, G.T. Moore and M.O. Scully, Editors, Plenum Press, N.Y., 1986.
3. I. Prigogine, *From Being to Becoming. Time and Complexity in the Physical Sciences*, W.H. Freeman & Co., N.Y., 1980.
4. E. Schrödinger, *Proceedings of the Cambridge Philosophical Society*, Vol. 32, 446 (1936).
J.L. Park, *American Journal of Physics*, Vol. 36, 211 (1968).
5. G.N. Hatsopoulos and J.H. Keenan, *Principles of General Thermodynamics*, Wiley & Sons, N.Y., 1965.
6. E.P. Gyftopoulos and G.P. Beretta, *What is the Second Law ?*, Proceedings of the IV International Symposium on Second Law Analysis of Thermal Systems, Roma, Italy, May, 1987.
7. I. Prigogine, F. Mayne, C. George and M. De Haan, *Proc. Natl. Acad. Sci. U.S.*, Vol. 74, 4152 (1977);
M. Thoediosopulu, A. Grecos and I. Prigogine, *Proc. Natl. Acad. Sci. U.S.*, Vol. 75, 1632 (1978);
B. Misra, I. Prigogine and M. Courbage, *Proc. Natl. Acad. Sci. U.S.*, Vol. 76, 4768 (1979).
8. W.H. Louisell, *Quantum Statistical Properties of Radiation*, Wiley & Sons, N.Y., 1973;
E.B. Davies, *Commun. Math. Phys.*, Vol. 39, 91 (1974);
P. Pearie, *Physical Review D*, Vol. 13, 857 (1976);
I. Bialynicki-Birula and J. Mycielski, *Ann. Phys. (N.Y.)*, Vol. 100, 62 (1976);
G. Lindblad, *Commun. Math. Phys.*, Vol. 48, 119 (1976);
Y. Garini, A. Frigerio, M. Verri, A. Kossakowski and E.C.G. Sudarshan, *Rep. Math. Phys.*, Vol. 13, 149 (1978);
R.F. Simmons jr. and J.L. Park, *Foundations of Physics*, Vol. 11, 297 (1981);
N. Gisin and C. Piron, *Lett. Math. Phys.*, Vol. 5, 379 (1981);
P. Caldirola and L.A. Lugiato, *Physica A*, Vol. 116, 248 (1982).
9. G.N. Hatsopoulos and E.P. Gyftopoulos, *Foundations of Physics*, Vol. 6, 15, 127, 439, 561 (1976).
10. Ref. 3, p. xvii.
11. Ref. 3, p. 165.
12. G.P. Beretta, *J. Math. Phys.*, Vol. 27, 305 (1986).
13. G. Nicolis and I. Prigogine, *Proc. Natl. Acad. Sci. U.S.*, Vol. 76, 6060 (1979);
P. Glansdorff and I. Prigogine, *Structure, Stability and Fluctuations*, Wiley & Sons, N.Y., 1980, p. 63.
14. G.P. Beretta, E.P. Gyftopoulos, J.L. Park and G.N. Hatsopoulos, *Nuovo Cimento B*, Vol. 82, 169 (1984);
G.P. Beretta, E.P. Gyftopoulos and J.L. Park, *Nuovo Cimento B*, Vol. 87, 77 (1985).
15. G.P. Beretta, *Int. J. of Theor. Phys.*, Vol. 24, 119 (1985).
16. G.P. Beretta, *Int. J. of Theor. Phys.*, Vol. 24, 1233 (1985).
17. G.P. Beretta, *Foundations of Physics*, Vol. 17, 365 (1987).
18. L. Onsager, *Physical Review*, Vol. 37, 405; Vol. 38, 2265 (1931).